

VibeCodeHPC: A Multi-LLM Agent Auto-Tuner for HPC Codes

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1. Background : Challenges of Applying CLI-Based LLM Agents to HPC Workflows

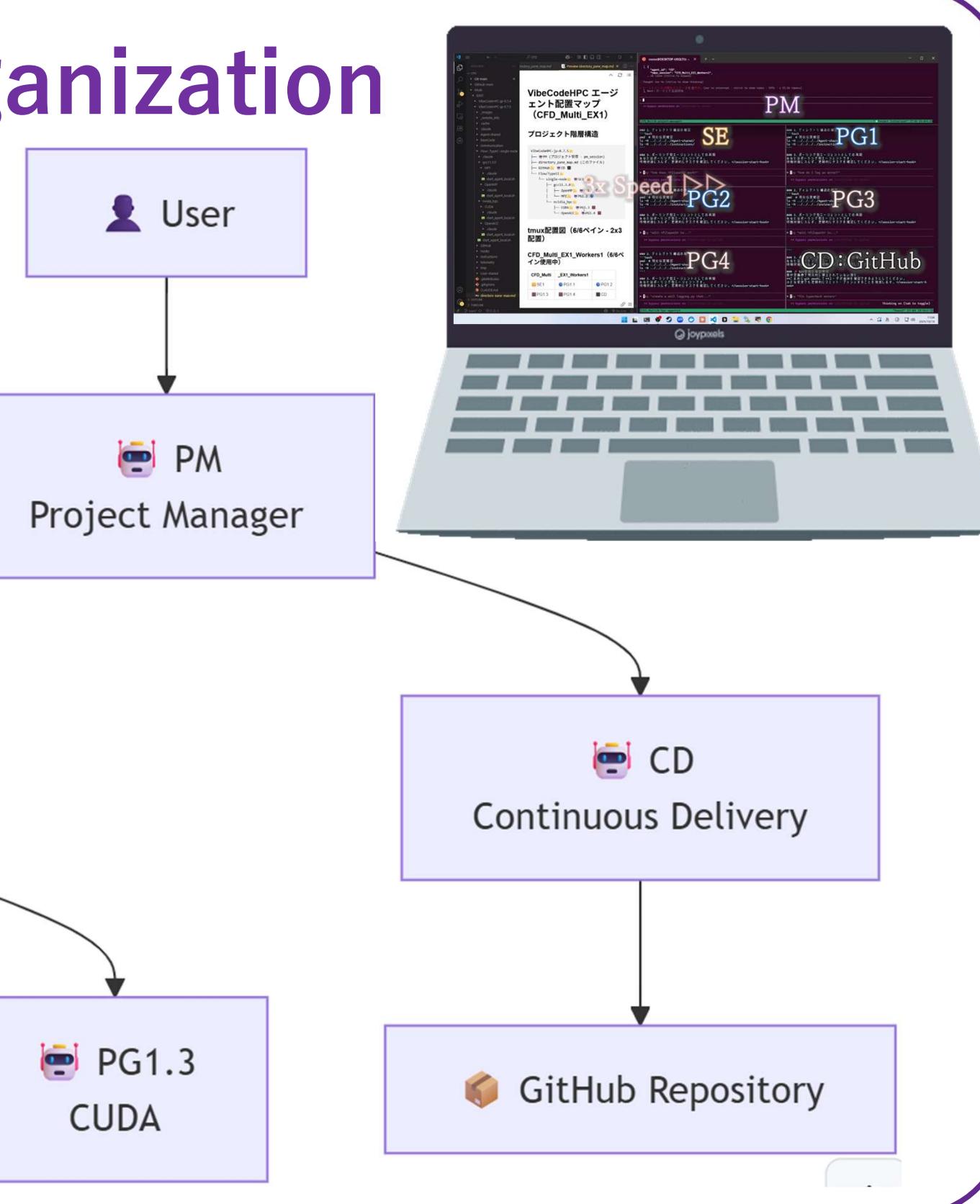
While CLI-based LLM agents like **Claude Code** enable automated environment setup, code editing, and debugging, their direct application to **supercomputers** remains difficult due to system-specific **constraints** such as complex **SSH** authentication, **vendor-specific** commands, restricted software installation, and **budget**-aware execution.

HPC program development is a highly complex **exploratory** task that requires simultaneous consideration of **performance**, distributed **heterogeneous** hardware architecture, and numerical **correctness**.

To address these challenges, we propose VibeCodeHPC[1][2], a CLI-based **multi-agent framework** that enables iterative prompting, mutual inspection, and **auto-tuning** of arbitrary code across heterogeneous HPC environments.

2. Dynamic Agent Organization

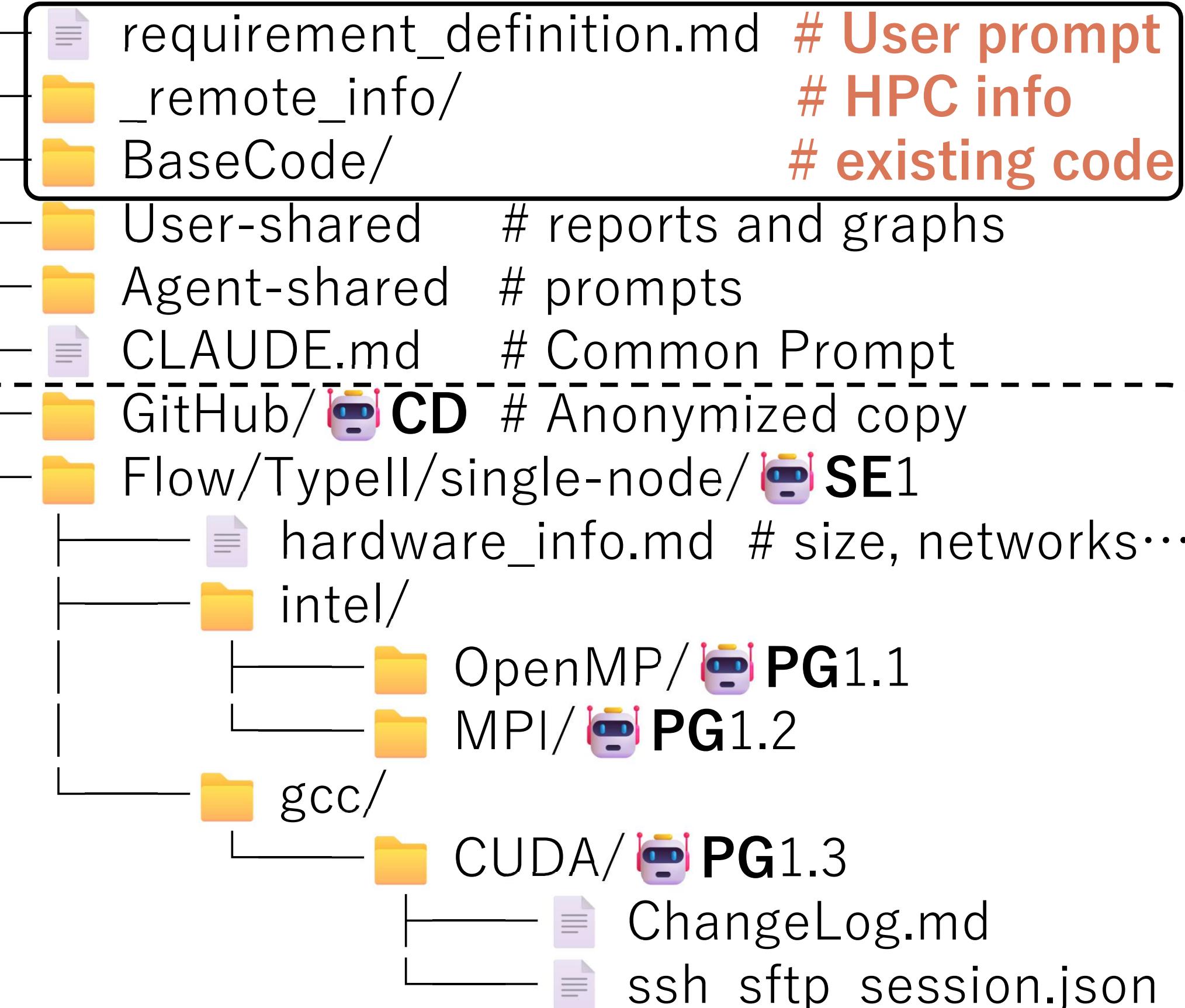
Each **Claude Code** agent communicates with others via shell script wrapping **Terminal Multiplexer (tmux)** functions



3. Project Structure

User prepares 3 items

VibeCodeHPC/ PM



Other implemented features

- ✓ **Hooks** prevent LLM from sleeping
- ✓ Manage supercomputer's **Budget**

Roadmaps

- ☐ Refactor as Skills (Multi CLIs support)
- ☐ Local LLM inference and training

URLs (arXiv, GitHub)

[1] Shun-ichiro Hayashi, Koki Morita, Daichi Mukunoki, Tetsuya Hoshino, Takahiro Katagiri, "VibeCodeHPC: An Agent-Based Iterative Prompting Auto-Tuner for HPC Code Generation Using LLMs", arXiv: 2510.00031, 2025.

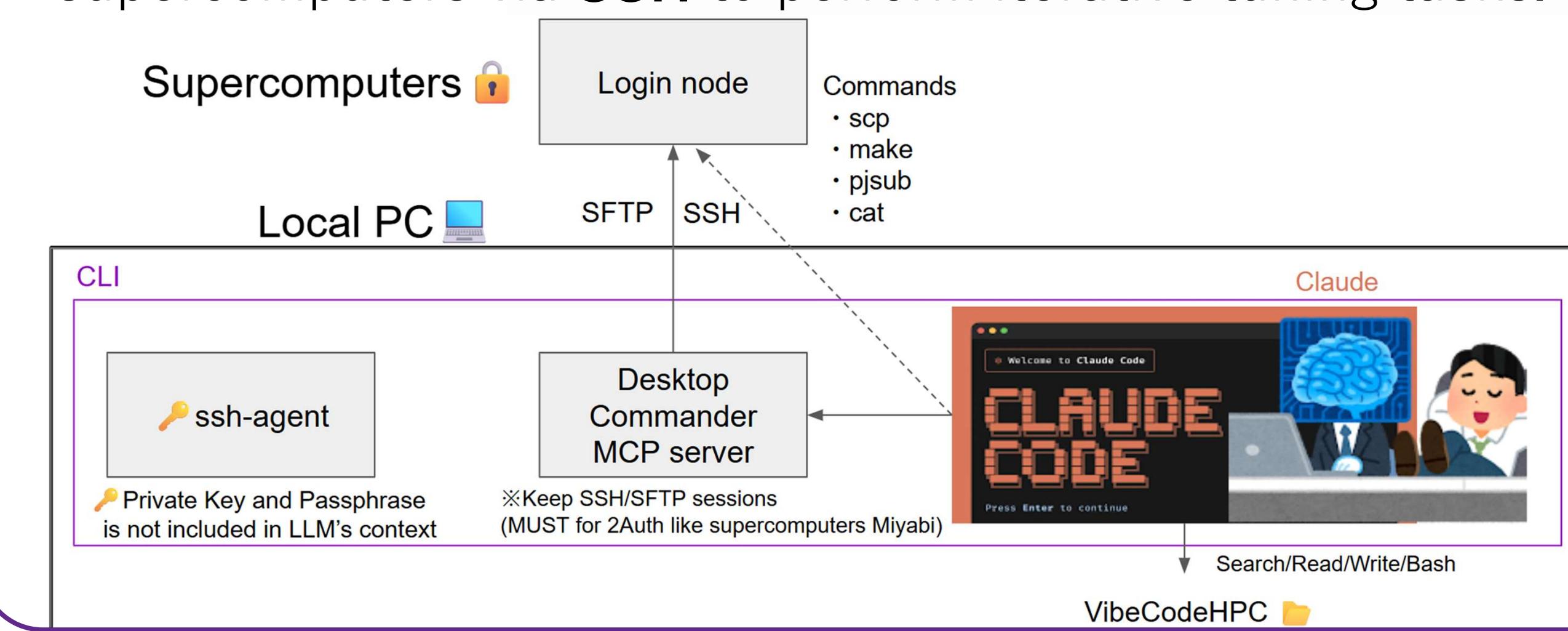
[2] Shun-ichiro Hayashi, VibeCodeHPC, <https://github.com/Katagiri-Hoshino-Lab/VibeCodeHPC-jp>

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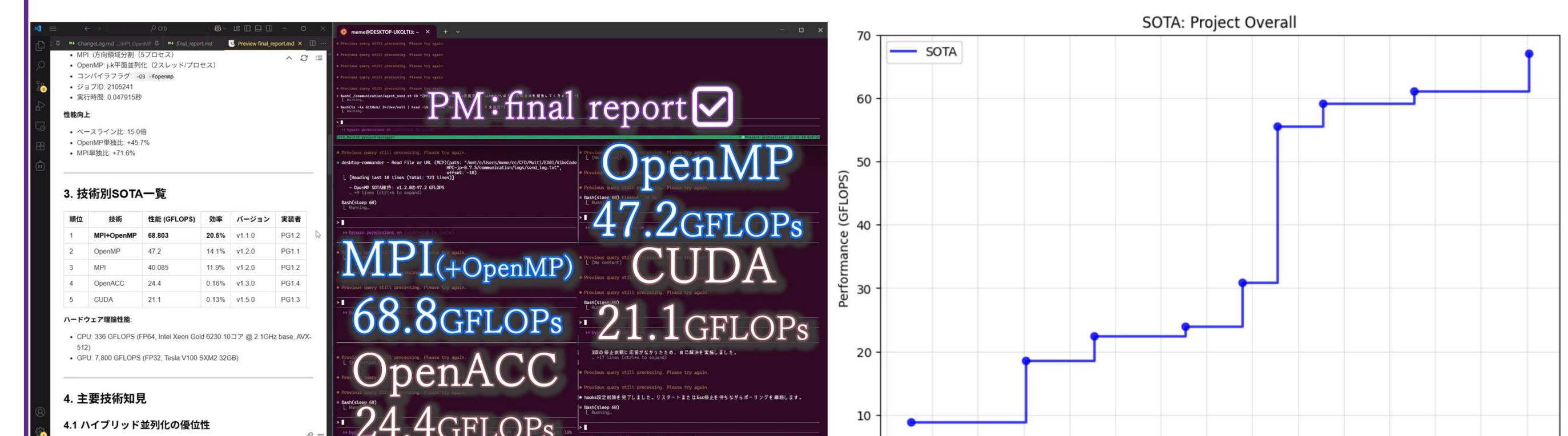
4. System Configuration

VibeCodeHPC runs on a **local PC** and launches multiple **Claude Code** agents. These agents interact with supercomputers via **SSH** to perform iterative tuning tasks.



5. Experiments (2 targets x3 runs)

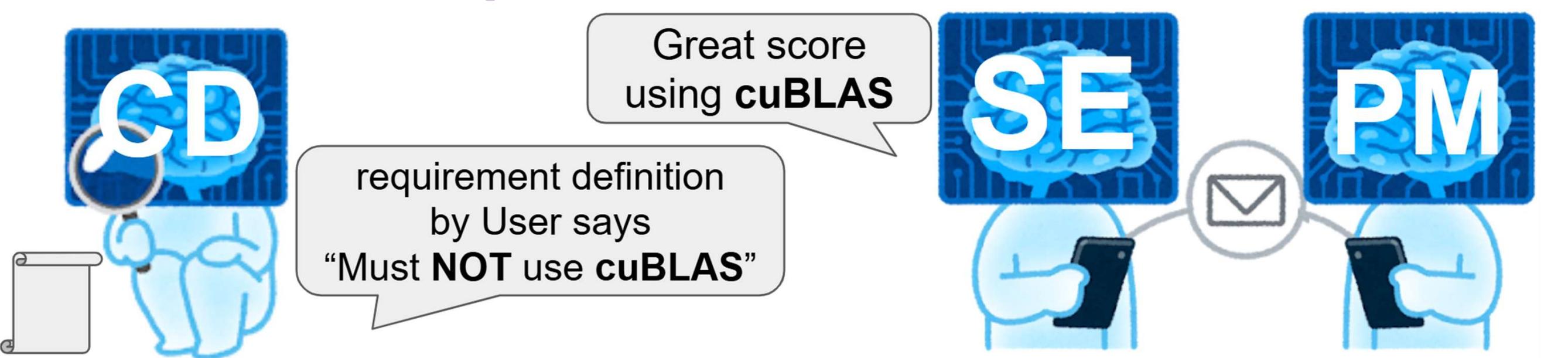
We compared **Multi-agents** & **Solo** agent to evaluate robustness in complex exploratory HPC tasks.



Target	Mode	EX1	EX2	EX3	Avg
CFD	Multi	68.8	77.8	67.1	71.23
	Solo	21.5	23.9	39.9	28.43
DGEMM	Multi	1385	3677	916	1993
	Solo	805	607	1098	837

$(A)(B) \equiv (C)$ Matrix product NVIDIA V100 GPUs x4

6. mutual inspection of Multi-agents



7. mutual cooperation of Multi-agents

